Numerical Algorithms for Visual Computing III 2011 Example Solutions for Assignment 7

Problem 1 (The Splitting Validation)

In order to show that the Douglas-Rachford Splitting $J_{DR}^{\lambda}(u) := [J_{\partial R}^{\lambda}(2J_{\partial S}^{\lambda} - I) + (I - J_{\partial S}^{\lambda})]u$ is a valid splitting scheme, we have to show $0 \in J_F(u) \Leftrightarrow u = J_{DR}^{\lambda}(u)$

	u	$=J_{DR}^{\lambda}(u)$
\Leftrightarrow	u	$= [J_{\partial R}^{\lambda}(2J_{\partial S}^{\lambda} - I) + (I - J_{\partial S}^{\lambda})]u$
\Leftrightarrow	u	$=2J_{\partial R}^{\lambda}J_{\partial S}^{\lambda}u-J_{\partial R}^{\lambda}u+u-J_{\partial S}^{\lambda}u$
\Leftrightarrow	u	$= 2(I + \lambda \partial R)^{-1}(I + \lambda \partial S)^{-1}u + (I + \lambda \partial R)^{-1}u$
		$+u - (I + \lambda \partial S)^{-1}u$
\Leftrightarrow	$(I + \lambda \partial R)(I + \lambda \partial S)u$	$= 2u - (I + \lambda \partial S)u$
		$+ (I + \lambda \partial R)(I + \lambda \partial S)u - (I + \lambda \partial R)u$
\Leftrightarrow	0	$= 2u - u - \lambda \partial S - u - \lambda \partial Ru$
\Leftrightarrow	-u	$= -u - \lambda Su - \lambda Ru$
\Leftrightarrow	u	$= (I + \lambda (\partial S + \partial R))u$
		∂F
\Leftrightarrow	u	$= (I + \lambda \partial F)u$
\Leftrightarrow	$(I+\lambda\partial F)^{-1}u$	= u
\Leftrightarrow	u	$=J_{\partial F}^{\lambda}(u)$
\Leftrightarrow	0	$\in J_F^{\lambda}(u)$

Problem 2 (The Conjugate Convexification)

Our task is to find the convex conjugate function

$$f^*(y) = \sup_{x \in D} y^{\top} x - f(x).$$

1. $f(x) = \exp(x)$:

$$f^*(y) = \sup_{x \in D} xy - \exp(x).$$

For a supremum, the derivative of f^* w.r.t. x should be zero, i.e. $(f^*)'(x) = y - \exp(x) \stackrel{!}{=} 0$. From this it follows $x = \log y$. Furthermore, $(f^*)''(x) = -\exp(x) < 0$, so this is indeed a supremum. By

plugging this result back into the definition of $f^*(y)$ and checking some cases, we arrive at

$$f^{*}(y) = \begin{cases} \log(y)y - y & (y > 0) \\ 0 & (y = 0) \\ \infty & (y < 0) \end{cases}$$

2. f(x) = |x|:

$$f^*(y) = \sup_{x \in D} xy - |x|.$$

Again, by deriving f^* w.r.t. x, we arrive at the necessary condition for a supremum: $y - \text{sgn}(x) \stackrel{!}{=} 0$. Plugging this back into f^* , we arrive at the following result:

$$f^*(y) = \begin{cases} 0 & (|y| \le 1) \\ \infty & (|y| > 1) \end{cases}$$

3. $f(x) = \frac{1}{2}x^2$:

$$f^*(y) = \sup_{x \in D} xy - \frac{1}{2}x^2.$$

After deriving f^* we arrive at $(f^*)'(x) = y - x \stackrel{!}{=} 0$. Plugging this back into f^* , we get

$$f^*(y) = \frac{1}{2}y^2.$$

4. $f(x) = a^{\top}x - b = x^{\top}a - b$:

$$f^*(y) = \sup_{x \in D} x^{\top} y - x^{\top} a + b.$$

Deriving w.r.t. to x we arrive at $(f^*)'(x) = y - a \stackrel{!}{=} 0$. Then the resulting convex conjugate function is

$$f^*(y) = \begin{cases} b & (y=a) \\ \infty & (y \neq a) \end{cases}$$

Problem 3 (Musings on Bregman Distance)

1. For the non-negativity we make use of the proper convex function property, i.e. $f(x) = x \cdot b - \beta$ as in (13.9). We consider

$$B_F(p,q) = F(p) - F(q) - (p-q) \cdot \nabla F(q) \ge 0$$

$$\Leftrightarrow p \cdot b - \beta - q \cdot b + \beta - (p-q) \cdot b \ge 0$$

$$\Leftrightarrow (p-q) \cdot b \ge (p-q) \cdot b,$$

which holds for any arbitrary b.

Another, more general method is to use a Taylor expansion for F(p) around position q:

$$F(p) = F(q) + (p-q)^{\top} \nabla F(q) + \frac{1}{2} (p-q)^{\top} HF(q)(p-q) + \mathcal{O}(q^3)$$

$$\Leftrightarrow \underbrace{F(p) - F(q) - (p-q)^{\top} \nabla F(q)}_{=B_F(p,q)} = \frac{1}{2} (p-q)^{\top} \underbrace{HF(q)}_{\geq 0} (p-q) + \mathcal{O}(q^3)$$

As we can see the left hand side of the equation is the Bregman distance and on the right hand side, we have a second order term. We have chosen F to be convex for all p, q, therefore, the Hessian on the right hand side is positive definite, i.e. the right hand side will become bigger than zero for $q \to 0$.

2. We only show this for the 1-D case. In order to assure convexity of the Bregman distance, we have to assure that the Hessian of the Bregman distance function is positive semi-definite. One way to check this is to consider the main minors of the Hessian. Let us now compute the derivatives.

$$\frac{\partial}{\partial p} B_F(p,q) = F'(p) - F'(q)$$
$$\frac{\partial}{\partial q} B_F(p,q) = -(p-q)F''(q)$$
$$\frac{\partial^2}{\partial p^2} B_F(p,q) = F''(p)$$
$$\frac{\partial^2}{\partial p \partial q} B_F(p,q) = -F''(q)$$
$$\frac{\partial^2}{\partial q^2} B_F(p,q) = -(p-q)F'''(q) + F''(q)$$

A good way to check positive semi-definiteness with the main minors. All determinants of the main minors have to be positive in order to assure positive semi-definiteness. The first minor F''(p) should be positive. This means that the distance function is at least convex in the first argument. However, the determinant for the second minor is given by $F''(p)(F''(q) - (p - q)F'''(q)) - (F''(q))^2$. Unfortunately, we cannot state anything here now for q, so it may or may not be F to be convex in q. Hence, resulting in the statement described. $B_F(p,q)$ is convex in its first argument, but not necessarily in its second.

$$B_{F_1+\lambda F_2}(p,q) = (F_1 + \lambda F_2)(p) - (F_1 + \lambda F_2)(q) - (p-q)\nabla(F_1 + \lambda F_2)(q)$$

= $F_1(p) + \lambda F_2(p) - F_1(q) - \lambda F_2(q) - (p-q)\nabla F_1(q) - (p-q)\nabla\lambda F_2(q)$
= $B_{F_1}(p,q) + \lambda B_{F_2}(p,q)$

Problem 4 (The Diverging Bregman)

At first, we consider the derivative of a function $f(x) = x \log x - x$, i.e. $f'(x) = \log x$. Applied on our given function, this gives $\nabla F(q) = (\log q_1, \log q_2, \dots, \log q_n)^{\top}$. This gives us

$$B_{F}(p,q) = F(p) - F(q) - (p-q) \cdot \nabla F(q) = \sum_{i} p_{i} \log p_{i} - \sum_{i} p_{i} - \sum_{i} q_{i} \log q_{i} + \sum_{i} q_{i} - \sum_{i} (p_{i} - q_{i}) \log q_{i} = \sum_{i} p_{i} \log \frac{p_{i}}{q_{i}} - \sum_{i} p_{i} + \sum_{i} q_{i}.$$

If we suppose now, that $\sum_i p_i = \sum_i q_i = 1$, this results in the so-called Kullback-Leibler divergence.

$$B_{KL}(p,q) = \sum p_i \log \frac{p_i}{q_i}.$$

Problem 5 (The ROF Lagrangian)

In this exercise we want to compute a PDE for the Ruder-Osher-Fatemi model. From the variational model

$$\int_{\Omega} \|\nabla u\| + \frac{\lambda}{2} \|u - f\|^2 \, \mathrm{d}x \, \mathrm{d}y$$

From this, we get the Lagrangian

$$F(x, y, u, u_x, u_y) = \sqrt{u_x^2 + u_y^2} + \frac{\lambda}{2}(u - f)^2$$

For the Euler-Lagrange equation

$$F_u - \frac{\mathrm{d}}{\mathrm{d}x}F_{u_x} - \frac{\mathrm{d}}{\mathrm{d}y}F_{u_y}$$

with the ingredients

$$F_u = \lambda(u - f)$$

$$F_{u_x} = \frac{u_x}{\sqrt{u_x^2 + u_y^2}}$$

$$F_{u_y} = \frac{u_y}{\sqrt{u_x^2 + u_y^2}}$$

we arrive at the PDE

$$\lambda(u-f) - \operatorname{div}\left(\frac{\nabla u}{\|\nabla u\|}\right)$$

Obviously this PDE is not differentiable at positions where $u_x = u_y = 0$. This problem is mostly being solved by artificially adding a small number ε in the norm, i.e. $\|\nabla u\|_{\varepsilon} := \sqrt{u_x^2 + u_y^2 + \varepsilon^2}$, resulting in

$$\lambda(u-f) - \operatorname{div}\left(\frac{\nabla u}{\|\nabla u\|_{\varepsilon}}\right)$$