

Mathematical Foundations of Computer Vision

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Assigned to: Tutorial at 03.11.2011, **this tutorial will start 16:45!**

Assignment 2 – The Concrete Basement Sheet

Two pages of small exercises cementing the basics.

Exercise No. 1 – Plain math

In this exercise, we consider the 2-D Euclidean space together with the two bases

$$B_1 := [e_1, e_2] \quad \text{and} \quad B_2 := \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} \quad (1)$$

- (a) Transform the vector $a_1 := (3, 3)^\top$ given in the basis B_1 to new coordinates b_1 w.r.t. B_2 . **(1pt)**
- (b) Transform the vector $b_2 := (2, -1)^\top$ given in the basis B_2 to new coordinates a_2 w.r.t. B_1 . **(1pt)**
- (c) Compute $\|a_1 - a_2\|_2$. **(2pts)**
- (d) Compute $\|b_1 - b_2\|_{A^{-\top} A^{-1}}$ making use of the metric induced by the canonical inner product expressed in the basis B_2 . Comment on your result: Did you expect it? **(4pts)**

Exercise No. 2 – Being innerly productive

We deal now with aspects of inner products:

- (a) Prove that the length of the vector $(x, y, z)^\top$ (in Cartesian coordinates) is given by

$$\sqrt{x^2 + y^2 + z^2} \quad (2)$$

by making use of the Theorem of Pythagoras. **(3pts)**

- (b) Show that for any positive definite, symmetric matrix $S \in \mathbb{R}^{3 \times 3}$, the mapping

$$\langle \cdot, \cdot \rangle_S : \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R} \quad \text{with} \quad \langle u, v \rangle_S = u^\top S v \quad (3)$$

is a valid inner product on \mathbb{R}^3 . **(3pts)**

Exercise No. 3 – Being crosswise productive

Let

$$v_1 := \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix} \quad \text{and} \quad v_2 := \begin{pmatrix} -1 \\ 2 \\ -2 \end{pmatrix} \quad (4)$$

- (a) Compute the angle between v_1 and v_2 as well as the length of the projection of v_1 onto v_2 . **(2pts)**
- (b) Compute a vector n orthogonal to v_1 and v_2 with $\|n\|_2 = 1$. **(2pts)**
- (c) Compute the area A of the parallelogram spanned by v_1 and v_2 . **(2pts)**

Exercise No. 4 – Plain stuff in 3-D

The *normal equation* of a 2-D plane P in 3-D reads as

$$\langle \vec{x} - \vec{a}, \vec{n} \rangle = 0 \quad (5)$$

where \vec{n} is orthogonal to the plane and \vec{a} contains the coordinates of a point in P . For $\|\vec{n}\|_2 = 1$, the formula (5) gives the *Hesse normal form*

$$\langle \vec{x}, \vec{n} \rangle - d = 0 \quad (6)$$

where $d \in \mathbb{R}$ is the distance between the origin and its closest point in P . In contrast, the *parameter form* of a plane is of the format

$$\vec{x} = \vec{x}_0 + \lambda_1 \vec{v}_1 + \lambda_2 \vec{v}_2 \quad \text{with } \lambda_1, \lambda_2 \in \mathbb{R} \quad (7)$$

where \vec{x}_0 is a point on P , and where \vec{v}_1, \vec{v}_2 give the basis of the 2-D subspace containing \vec{x}_0 .

Now, let a *point light source* be given at the point $p := (1, 1, 1)^\top$. Let the light shine onto a *triangle patch* determined by the vertices

$$A := \begin{pmatrix} 1 \\ 4/3 \\ 1/3 \end{pmatrix}, \quad B := \begin{pmatrix} 1 \\ 3/2 \\ 1 \end{pmatrix} \quad \text{and} \quad C := \begin{pmatrix} 5/2 \\ 1/2 \\ 0 \end{pmatrix} \quad (8)$$

Compute the area of the shadow of the triangle patch given by (A, B, C) on the plane $4x + 6y - 3z = 19$. **(10pts)**