

# Differential Geometric Aspects in Image Processing

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## Problem C5.1

i) Fixing  $\theta$  gives a the radial geodesics in arc-length parametrisation.

ii) Follows from the systems of ode's for a geodesic

$$\rho'' + \Gamma_{11}^1(\rho')^2 + 2\Gamma_{12}^1\rho'\theta' + \Gamma_{22}^1(\theta')^2 = 0 \quad (1)$$

$$\theta'' + \Gamma_{11}^2(\rho')^2 + 2\Gamma_{12}^2\rho'\theta' + \Gamma_{22}^2(\theta')^2 = 0 \quad (2)$$

applied to a radial geodesic ( $\theta' = 0$ ).

iii) From the definition of the Christoffel symbols we have that

$$\sigma_{\rho\rho} = \Gamma_{11}^1\sigma_\rho + \Gamma_{11}^2\sigma_\theta + L_1N$$

Taking the scalar product with  $\sigma_\rho$  and  $\sigma_\theta$  respectively we obtain

$$\Gamma_{11}^1E + \Gamma_{11}^2F = \langle \sigma_{\rho\rho}, \sigma_\rho \rangle = \frac{1}{2}E_\rho$$

$$\Gamma_{11}^1F + \Gamma_{11}^2G = \langle \sigma_{\rho\rho}, \sigma_\theta \rangle = F_\rho - \frac{1}{2}E_\theta.$$

$\Gamma_{11}^1 = E_\rho = 0$  follows from the first and  $F_\rho = 0$  from the second one.

iv) Let  $\alpha(t)$  be the geodesic circle through  $q \in V \setminus \{p\}$  and let  $\gamma(s)$  be the radial geodesic through  $q$  in arc-length parametrisation. Then,  $F(\rho, \theta) = \left\langle \frac{d\alpha}{dt}, \frac{d\gamma}{ds} \right\rangle$  for all  $\rho > 0$ .

Fixing  $\theta = \text{const}$  we get that  $\lim_{\rho \rightarrow 0} F(\rho, \theta) = \lim_{\rho \rightarrow 0} \left\langle \frac{d\alpha}{dt}, \frac{d\gamma}{ds} \right\rangle = 0$

## Problem C5.2

i) The tangents of the  $2D$  level sets  $u$  are given by  $(-u_y, u_x)$ , since  $\vec{n} = \frac{\nabla u}{|\nabla u|}$ . Moreover, since the projections of the level sets of  $u$  coincide with geodesic circles, this implies that  $\Pi(\vec{t}^\alpha) = c(-u_y, u_x)$

ii) Denoting  $\vec{t}^\alpha = (T_1, T_2, T_3)$  we obtain from i) that

$$(T_1, T_2) = c(-u_y, u_x).$$

Furthermore, we have that  $N = \frac{(-p, -q, 1)}{\sqrt{1+p^2+q^2}}$  and  $\langle \vec{t}^\alpha, N \rangle = 0$ . Therefore

$$T_3 = c(qu_x - pu_y).$$

Finally we compute the constant  $c$  s.t.  $\vec{t}^\alpha$  is normalised. Namely  $|\vec{t}^\alpha| = |c|(-u_y, u_x, qu_x - pu_y)| = 1$ , thus  $c = \sqrt{u_x^2 + u_y^2 + (qu_x - pu_y)^2}$  and the result follows.